## An Implementable Scheme for Universal Lossy Compression

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 $X^n$  Encoder  $m \in \{1, \dots, 2^{nR}\}$  Decoder  $\hat{X}^n$ 

•  $\{X_i\}_{i\in\mathbb{Z}}$ : discrete-valued stochastic source

Rate-Distortion Coding

• To each coding scheme a distortion D is assigned as

$$D = \operatorname{E} d_n(X^n, \hat{X}^n) \triangleq \frac{1}{n} \sum_{i=1}^n \operatorname{Ed}(X_i, \hat{X}_i)$$

• The goal is to find a coding scheme that for each given  $\alpha>0$  minimizes the Lagrangian cost  $R+\alpha D$ 

Universal lossy compression

- The performance of each coding scheme depends on the source distribution.
- Does there exist a universal coding scheme that works well for any stationary ergodic source?
- Yes.
- Are there practical universal lossy compression algorithms?
- For a long time it was believed that no such algorithm exists.

- Consider binary alphabet  $\mathcal{X} = \hat{\mathcal{X}} = \{0, 1\}$
- Let  $\mathbf{m}(y^n)$  denote a  $2 \times 2^k$  matrix defining the  $(k+1)^{\text{th}}$  order empirical distribution of  $y^n$
- Example: k = 2,

Empirical distribution

$$\mathbf{m}(y^n) = \begin{bmatrix} m_{0,00} & m_{0,01} & m_{0,10} & m_{0,11} \\ m_{1,00} & m_{1,01} & m_{1,10} & m_{1,11} \end{bmatrix}$$

For  $b \in \{0, 1\}$ 

$$m_{b,00}(y^n) = \frac{1}{n} |\{i : y_i = b, y_{i-2}^{i-1} = [0,0]\}|$$

- Conditional empirical entropy of  $y^n$  is defined as
- $H_k(y^n) = H(Y_{k+1}|Y^k)$  when  $Y^{k+1}$  is distributed according to  $\mathbf{m}$
- In the previous example:

Conditional empirical entropy

$$H_2(y^n) = \sum_{b_1, b_2} (m_{0, [b_1, b_2]} + m_{1, [b_1, b_2]}) \mathcal{H}(m_{0, [b_1, b_2]}, m_{1, [b_1, b_2]})$$

• Let  $\alpha_1 = m_{0,[b_1,b_2]}$  and  $\alpha_2 = m_{1,[b_1,b_2]}$ . Then

$$\mathcal{H}(\alpha_1, \alpha_2) = H(X),$$

where  $X \sim \text{Bern}(\frac{\alpha_1}{\alpha_1 + \alpha_2})$ 

Universal lossy compression algorithm

### An Exhaustive Search Algorithm:

For coding sequence  $x^n$ , find sequence  $\hat{x}^n$  such that

$$\hat{x}^n = \arg\min_{y^n} \left[ H_k(y^n) + \alpha d_n(x^n, y^n) \right],$$

and describe it to the decoder using Lempel-Ziv algorithm.

#### Theorem:

For any stationary ergodic source **X** and  $k = o(\log n)$ ,

$$\mathrm{E}\left[\ell_{\mathrm{LZ}}(\hat{X}^n) + \alpha d(X^n, \hat{X}^n)\right] \to \min_{D}[R(\mathbf{X}, D) + \alpha D]$$

Exponential Complexity

Compression via Simulated Annealing

- To each sequence  $y^n$  assign energy  $\mathcal{E}(y^n) = H_k(y^n) + \alpha d_n(x^n, y^n)$
- For T > 0, define a distribution on the space of all possible reconstructions as  $p_T(y^n) \propto e^{-\mathcal{E}(y^n)/T}$
- Simulated annealing: gradually decreasing temperature while sampling from the distribution; finds  $\hat{x}^n$  such that

$$\mathcal{E}(\hat{x}^n) \approx \min_{y^n} \mathcal{E}(y^n)$$

Theorem:[JW08]

Let  $\mathbf{X}$  be a stationary and ergodic source. Then

$$\lim_{n\to\infty}\lim_{r\to\infty}\mathbb{E}\left[\frac{1}{n}\ell_{\mathsf{LZ}}\left(\hat{X}^n_{\alpha,r}(X^n)\right)+\alpha d_n(X^n,\hat{X}^n)\right]=\min_{D\geq 0}\left[R(\mathbf{X},D)+\alpha D\right].$$

No bound on the required number of iterations

Another approach

(P1):  $\min_{y^n} \left[ H_k(y^n) + \alpha d_n(x^n, y^n) \right]$ 

(P2):  $\min_{y^n} \left[ \sum_{b_{k+1}, \mathbf{b}} \sum_{\mathbf{b}} \lambda_{b_{k+1}, \mathbf{b}} m_{b_{k+1}, \mathbf{b}} (y^n) + \alpha d_n(x^n, y^n) \right]$ • Assume that we could find a set of coefficients  $\{\lambda_{b_{k+1}, \mathbf{b}}\}_{b_{k+1}, \mathbf{b}}$  such that

- (P1) and (P2) have the same minimizersWhy are we interested in this new representation?
- Note:

$$\sum_{k+1,\mathbf{b}} \left[ \lambda_{b_{k+1},\mathbf{b}} m_{b_{k+1},\mathbf{b}}(y^n) + \alpha d_n(x^n, y^n) \right]$$

$$= \frac{1}{n} \sum_{b_{k+1},\mathbf{b}} \left[ \lambda_{b_{k+1},\mathbf{b}} \sum_{i=1}^n \mathbf{1}_{y_{i-k}^i = [\mathbf{b}, b_{k+1}]} + \alpha d(x_i, y_i) \right]$$

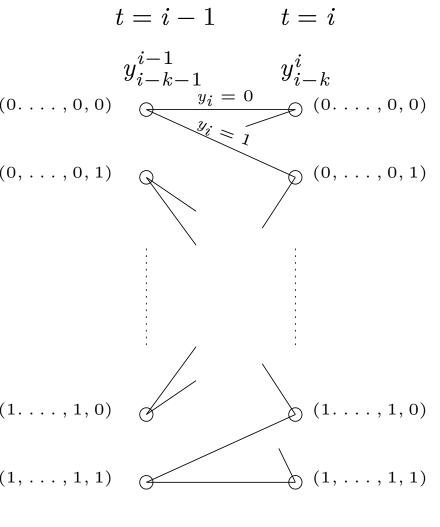
$$= \frac{1}{n} \sum_{i=1}^n \left[ \lambda_{y_i, y_{i-k}^{i-1}} + \alpha d(x_i, y_i) \right].$$

• (P2) can be solved using Viterbi algorithm

Viterbi algorithm

- Let the state at time i be  $\mathbf{s}_i = (y_{i-k}^{i-1}, y_i)$
- One-to-one correspondence between the paths inside the trellis, sequence of states  $\{s_i\}_{i=1}^n$ , and also sequences  $y^n$
- We want to find the path in the trellis minimizing  $\sum_{i=1}^{n} w_i(y_{i-k}^i)$ , where

$$w_i(\mathbf{s_i}) = \lambda_{y_i, y_{i-k}^{i-1}} + \alpha d(x_i, y_i)$$



Do such coefficients exist?

Practical implementation of the new algorithm

Simulation results

Simulation results

• Yes

#### Lemma

(P1) and (P2) have the same minimum values, if the coefficients are chosen according to

$$\lambda_{b_{k+1},\mathbf{b}} = \frac{\partial}{\partial m_{b_{k+1},\mathbf{b}}} H(\mathbf{m}) |_{\mathbf{m}_n^*}$$

where  $\mathbf{m}_n^* = \mathbf{m}_n^*(\hat{x}^n)$ , where  $\hat{x}^n$  is a minimizer of (P1)

- Do we have access to  $\hat{x}^n$ ? Of course not!
- But, we can find an approximate version of  $\mathbf{m}_n^*$  by solving a non-convex optimization problem.
- We need to approximate the coefficients
- Solving the non-convex optimization problem is hard
- Try simpler approximations for  $\mathbf{m}^*$ , like  $\mathbf{m}(x^n)$ - works well for small distortions
- For larger distortions, we can use iterative approach

